



## **The meaning of curvature**

A distance geometric approach

**Markvorsen, Steen**

*Publication date:*  
2009

[Link back to DTU Orbit](#)

*Citation (APA):*

Markvorsen, S. (Author). (2009). The meaning of curvature: A distance geometric approach. Sound/Visual production (digital)

---

### **General rights**

Copyright and moral rights for the publications made accessible in the public portal are retained by the authors and/or other copyright owners and it is a condition of accessing publications that users recognise and abide by the legal requirements associated with these rights.

- Users may download and print one copy of any publication from the public portal for the purpose of private study or research.
- You may not further distribute the material or use it for any profit-making activity or commercial gain
- You may freely distribute the URL identifying the publication in the public portal

If you believe that this document breaches copyright please contact us providing details, and we will remove access to the work immediately and investigate your claim.

# THE MEANING OF CURVATURE

## A DISTANCE GEOMETRIC APPROACH

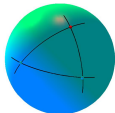
### Manifold Learning

On the island of Hven

August 17-21, 2009

Steen Markvorsen

DTU Mathematics



# Synopsis

## 1 Curvature sensitive geodesic sprays

# Synopsis

- 1 Curvature sensitive geodesic sprays
- 2 Structural results



# Synopsis

- 1 Curvature sensitive geodesic sprays
- 2 Structural results
- 3 Curvature controlled comparison theory

# Synopsis

- 1 Curvature sensitive geodesic sprays
- 2 Structural results
- 3 Curvature controlled comparison theory
- 4 Length space analysis

# General case

Definition (Geodesics in a Riemannian manifold  $(M, g)$ )

With a given starting point  $p$  and a unit initial direction  $\dot{\gamma}(0)$  in the tangent space to  $M$  at  $p$  :

$$\frac{D\dot{\gamma}(t)}{dt} = 0 \quad .$$

# Sphere case

Geodesic spray on the sphere

# Ellipsoid case, positive curvature

Geodesic spray on an ellipsoid

# Hyperboloid of one sheet, negative curvature

Geodesic spray on an elliptic hyperboloid of one sheet

# Geodesic sprays converge when the curvature is positive

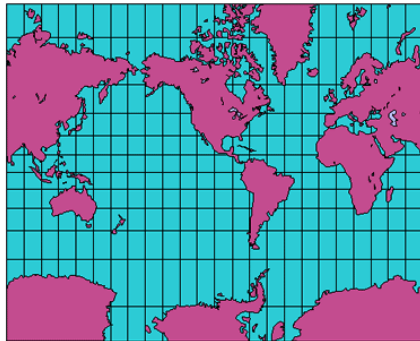
Geodesic spray in a curvature-colored map of the ellipsoid

# Geodesic sprays diverge when the curvature is negative

Geodesic spray in a curvature-colored map of the hyperboloid

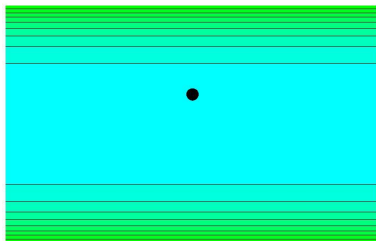


# Special maps: Mercator map of the globe



The well known Mercator map from any atlas

# Conformally flat Mercator map of the sphere



The Mercator map with conformal factor coloring

# Conformal curvature example

## Proposition

*A conformally flat metric*

$$g(u, v) = e^{-2\psi(u, v)} g_0(u, v)$$

*has the Gaussian curvature*

$$K(u, v) = e^{2\psi(u, v)} \Delta \psi(u, v)$$

# Conformal positive curvature example

Example (Constant curvature  $K = 1$ )

With conformal factor

$$e^{-2\psi(u,v)} = \cosh^{-2}(v)$$

we have

$$\psi(u, v) = \log(\cosh(v))$$

$$\Delta\psi(u, v) = 1 - \tanh^2(v)$$

so that

$$K(u, v) = e^{2\psi(u,v)} \Delta\psi(u, v) = \cosh^2(v) (1 - \tanh^2(v)) = 1 \quad .$$

# Geodesics in the conformal Mercator map projection of the sphere

Two geodesics in conformally colored map of the sphere

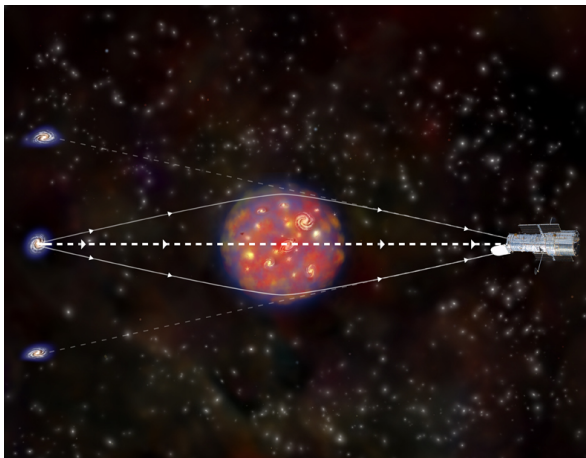
# Geodesics in the conformal Mercator map projection of the sphere

Two geodesics seemingly diverging?

# Geodesics in the conformal Mercator map projection of the sphere

Geodesic spray in the Mercator map

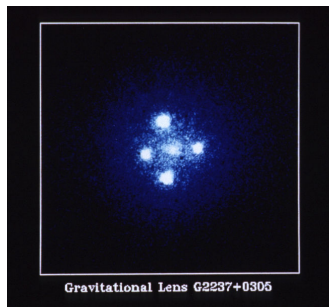
# Gravitational lensing



Gravitational lens principle

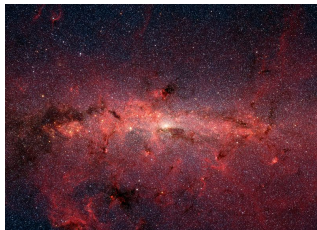


# Gravitational lensing



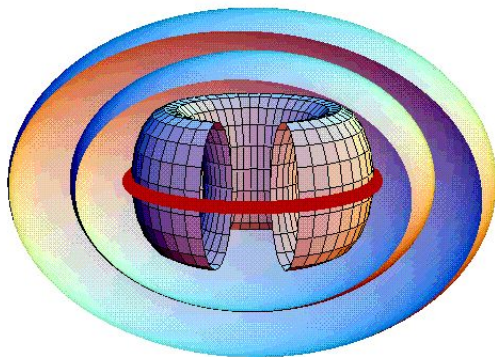
A specific gravitational lens as seen by the Hubble telescope

# Black holes everywhere



A black hole resides at the center of every galaxy

# Rotating black holes



The structure of a Kerr solution

# Equations for gravity

Field equations (A. Einstein, 1915)

$$\text{Ric} - \frac{1}{2} S g = 8\pi\kappa T$$

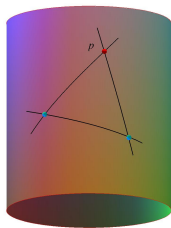
# Lines and nonnegative curvature

## Theorem (Cohn-Vossen, 1935)

*Let  $F$  be a surface which satisfies the following conditions:*

- *$F$  is geodesically complete.*
- *$F$  has nonnegative Gauss curvature everywhere.*
- *$F$  contains a geodesic line.*

*Then  $F$  is a generalized CYLINDER.*



Flat standard cylinder  $\mathbb{S}^1 \times \mathbb{R}^1$

# Cosmologies

Theorem (Cheeger–Gromoll 1971, Yau 1982, —, Newman 1990)

*Let  $M$  be a space time which satisfies the following conditions:*

- *$M$  is timelike geodesically complete.*
- *$M$  has nonnegative timelike Ricci curvature everywhere.*
- *$M$  contains a timelike line.*

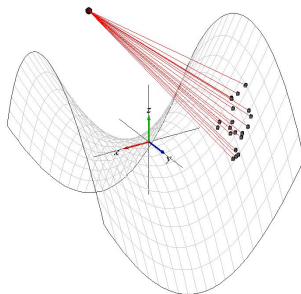
*Then  $M$  is a generalized CYLINDER.*

# Distance Geometric Analysis

Geodesic distance contact to 1D submanifold in a 2D 'ambient' surface

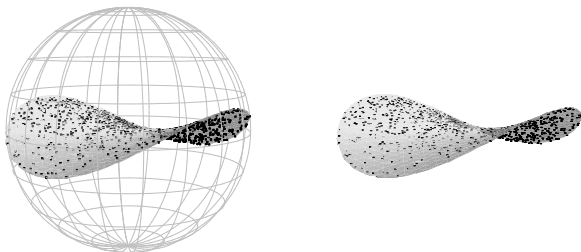


# Distance Geometric Analysis



Geodesic distance contact to a 2D submanifold in 3D flat space

# Extrinsic disk of submanifold



Extrinsic disk of a surface

# Distance Geometric Analysis

## Proposition (Laplacian comparison technique)

$$\begin{aligned}\Delta^P \psi(r(x)) &\leq (\psi''(r(x)) - \psi'(r(x))\eta_w(r(x))) \|\nabla^P r\|^2 \\ &\quad + m\psi'(r(x))(\eta_w(r(x)) - h(r(x))) \\ &\leq L\psi(r(x)) = -1 = \Delta^P E(x) \quad ,\end{aligned}$$

where

$$L f(r) = f''(r) g^2(r) + f'(r) ((m - g^2(r)) \eta_w(r) - m h(r))$$

*is a special tailor made rotationally symmetric Poisson solution in a suitably chosen warped product comparison space.*

# Solutions to Laplacian processes on manifolds

$$H(x, y, t) = \sum_{i=0}^{\infty} e^{-\lambda_i t} \phi_i(x) \phi_i(y)$$

$$G(x, y) = \int_0^{\infty} H(x, y, t) dt$$

$$E(x) = \int_P G(x, y) dy$$

$$\mathcal{A} = \int_P E(x) dx$$

# Equations of Laplacian processes on manifolds

$$\left( \Delta_x^P - \frac{\partial}{\partial t} \right) H(x, y, t) = 0$$

$$\Delta_x^P G(x, y) = 0$$

$$\Delta_x^P E(x) = -1$$

### Theorem (SM and V. Palmer, GAFA, 2003)

*Let  $P^m$  be a complete minimally immersed submanifold of an Hadamard–Cartan manifold  $N^n$  with sectional curvatures bounded from above by  $b \leq 0$ . Suppose that either  $(b < 0 \text{ and } m \geq 2)$  or  $(b = 0 \text{ and } m \geq 3)$ .*

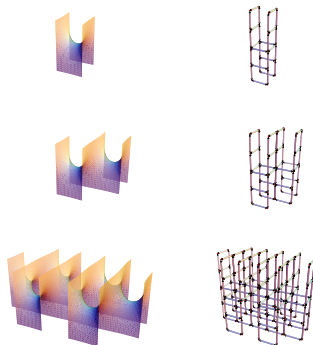
*Then  $P^m$  is transient.*

# Minimality



Extrinsic disks of minimal surfaces in  $\mathbb{R}^3$

# Minimality



Scherk's doubly periodic minimal surface in  $\mathbb{R}^3$  and a corresponding minimal web



# Intrinsic mean exit time expansion

Theorem (A. Gray and M. Pinsky, 1983)

Let  $B_r^m(p)$  denote an intrinsic geodesic ball of small radius  $r$  and center  $p$  in a Riemannian manifold  $(M^m, g)$  which has scalar curvature  $\tau(p)$  at the center point  $p$ .

Then the mean exit time from  $B_r(p)$  for Brownian particles starting at  $p$  is

$$E_r(p) = \frac{r^2}{2m} + \frac{\tau(p) r^4}{12m^2(m+2)} + r^5 \varepsilon(r) \quad ,$$

where  $\varepsilon(r) \rightarrow 0$  when  $r \rightarrow 0$ .

# Extrinsic mean exit time expansion

Theorem (A. Gray, L. Karp, and M. Pinsky, 1986)

*Let  $P^2$  be a 2D surface in  $\mathbb{R}^3$ . For a point  $p$  in  $P$  we let  $D_r(p)$  denote the extrinsic geodesic disk of small radius  $r$  and center  $p$ .*

*Then the mean exit time from  $D_r(p)$  for Brownian particles starting at  $p$  is*

$$E_r(p) = \frac{r^2}{4} + \frac{r^4}{6}(H^2 - K) + r^5\varepsilon(r) \quad ,$$

*where  $\varepsilon(r) \rightarrow 0$  when  $r \rightarrow 0$ .*

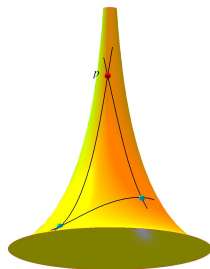
# Slim, normal, and fat triangles

## Theorem (Alexandrov, Toponogov, 60)

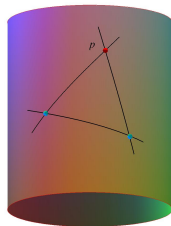
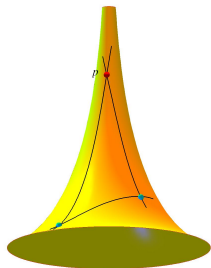
*The (sectional) curvatures of a Riemannian manifold  $M^n$  satisfy  $\text{curv}(M) \geq 1$  if and only if every geodesic triangle  $\Delta$  in  $M^n$  and comparison triangle  $\Delta^*$  (with same edge lengths as  $\Delta$ ) in the unit sphere  $\mathbb{S}_1^2$  satisfy the fatness condition:*

$$\alpha_i \geq \alpha_i^*, \quad i = 1, 2, 3 \quad .$$

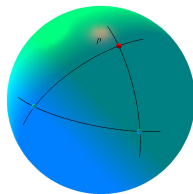
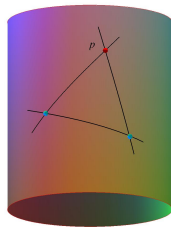
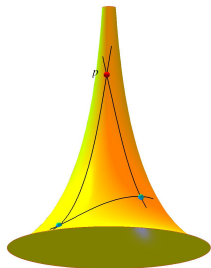
# Sign of Gaussian Curvature



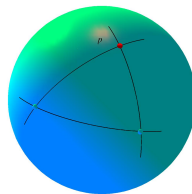
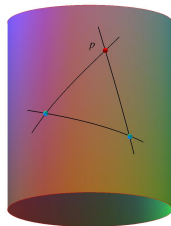
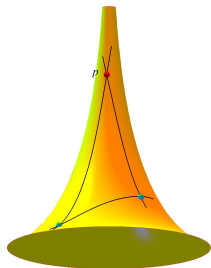
# Sign of Gaussian Curvature



# Sign of Gaussian Curvature

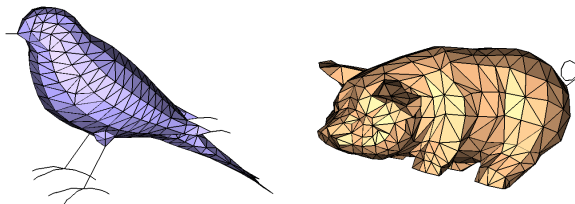


# Sign of Gaussian Curvature



Negative, zero, and positive curvature

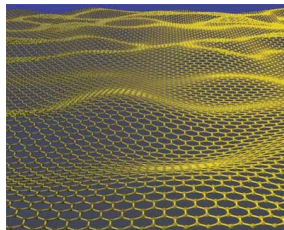
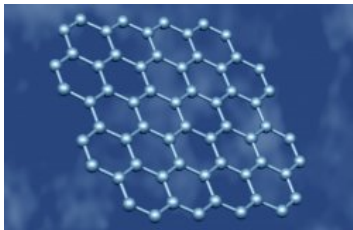
# Objects admitting geodesic distances



Length spaces



# Objects admitting geodesic distances



Graphene landscape

# Other measures of size and shape

## Definition

Let  $X$  denote a compact metric space.

For any  $q$ -tuple  $\{x_1, \dots, x_q\}$  of points in  $X$  we let  $\text{xt}_q$  denote the average total distance

$$\text{xt}_q(x_1, \dots, x_q) = \binom{q}{2}^{-1} \sum_{i < j}^n \text{dist}(x_i, x_j) \quad .$$

Consider the maximum, the  $q$ - extent of  $X$ :

$$\text{xt}_q(X) = \max_{x_1, \dots, x_q} \text{xt}_q(x_1, \dots, x_q) \quad .$$

# Other measures of *size*

## Theorem (O. Gross, 1964)

*Let  $X$  be a compact connected metric space.*

*Then there is a unique positive real number  $\text{rv}(X)$  – the rendez vous value of  $X$  – with the following property:*

*For each finite collection of points  $x_1, \dots, x_q$  in  $X$  there exists a point  $y$  in  $X$  such that*

$$(1/q) \sum_{i=1}^q \text{dist}(x_i, y) = \text{rv}(X) .$$

# Large scale results for extents and rendez vous values

Theorem (K. Grove and SM, 1997)

*Let  $X^n$  be an Alexandrov space with*

$$\text{curv}(X) \geq 1 .$$

*Then*

$$\text{xt}_\infty(X) \leq \pi/2 \quad \text{and}$$

$$\text{rv}(X) \leq \pi/2 .$$

*One (and thence both) equality occurs if and only if  $X^n$  is a spherical suspension over an "equatorial" Alexandrov space  $\Theta^{n-1}$  with  $\text{curv}(\Theta) \geq 1$  .*

# Large scale recognition stability

Theorem (G. Perelman and T. Yamaguchi, 1991)

*Let  $X^n$  be a compact Alexandrov space with  $\text{curv}(X) \geq k$ .*

*Then there exists a positive real number  $\varepsilon = \varepsilon(X)$  such that every other compact Alexandrov space  $Y^n$  with  $\text{curv}(Y) \geq k$  and Gromov–Hausdorff distance  $d_{GH}(X, Y) \leq \varepsilon$  is homeomorphic to the given space  $X^n$ .*

Reference: F. Memoli, *Gromov–Hausdorff distances in Euclidean spaces*.

## B. Springborn, P. Schröder, and U. Pinkall

ACM Transactions on Graphics, Vol. 27, Article 77, No. 3, August 2008:

### Definition

Two discrete metrics  $\mathcal{L}$  and  $\bar{\mathcal{L}}$  on  $M$  are (discretely) *conformally equivalent* if, for some assignment of numbers  $\psi_i$  to the vertices  $v_i$ , the metrics are related by

$$\mathcal{L}_{ij} = e^{-(\psi(i)+\psi(j))} \bar{\mathcal{L}}_{ij}$$

## B. Springborn, P. Schröder, and U. Pinkall

ACM Transactions on Graphics, Vol. 27, Article 77, No. 3, August 2008:

### Definition

Two discrete metrics  $\mathcal{L}$  and  $\bar{\mathcal{L}}$  on  $M$  are (discretely) *conformally equivalent* if, for some assignment of numbers  $\psi_i$  to the vertices  $v_i$ , the metrics are related by

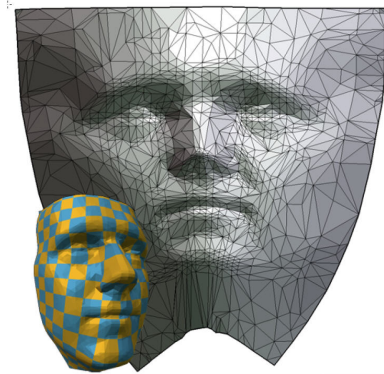
$$\mathcal{L}_{ij} = e^{-(\psi(i)+\psi(j))} \bar{\mathcal{L}}_{ij}$$

Compare with the smooth definition of conformal maps

$$g(u, v) = e^{-2\psi(u,v)} g_0(u, v)$$

## B. Springborn, P. Schröder, and U. Pinkall

ACM Transactions on Graphics, Vol. 27, Article 77, No. 3, August 2008



Conformal representation



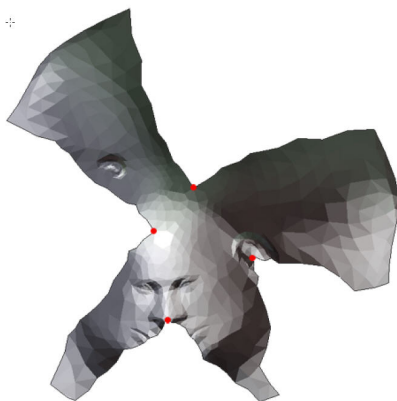
## B. Springborn, P. Schröder, and U. Pinkall

ACM Transactions on Graphics, Vol. 27, Article 77, No. 3, August 2008



Conformal representation

# Relaxing curvature along the image boundary



Conformal representation with cone singularities

# Conclusion

Curvature matters on all scales:

# Conclusion

Curvature matters on all scales:

- 1 Globally, locally, and micro-locally

# Conclusion

Curvature matters on all scales:

- 1 Globally, locally, and micro-locally
- 2 In smooth and in discrete geometry

# Conclusion

Curvature matters on all scales:

- 1 Globally, locally, and micro-locally
- 2 In smooth and in discrete geometry

Thank you for your attention!

